Multi-Path General-to-Specific Modelling with OxMetrics

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Outline:

1. General-to-Specific (GETS) modelling:
   $\rightarrow$ Motivation, properties, advantages, disadvantages

2. The basics of OxMetrics 5:
   $\rightarrow$ Loading, editing and transforming data (logs, differencing), creating "special" series (cointegration relations, trends, etc.)

3. An overview of Autometrics:
   $\rightarrow$ Key concepts and characteristics

4. Single-equation modelling with Autometrics
   $\rightarrow$ Formulation, Advanced Autometrics settings, fixing variables, example (2007 Econometric Game, Q1)

5. Multiple-equation modelling with Autometrics
   $\rightarrow$ Formulation, fixing variables, example (2007 Econometric Game, Q2)

Common (in-sample) modelling strategies:

1. Select model that minimises information criterion

2. Simple-to-general

3. "1-shot" General

4. Single-path GETS

• Multi-Path GETS: Combines 1 and 4 iteratively

• Multi-Path GETS algorithms: Hoover and Perez (1999), PcGets (Hendry and Krolzig 2001, 2005), Autometrics (Doornik and Hendry 2007a, Doornik 2009), AutoSEARCH (Sucarrat and Escribano 2009, Sucarrat 2009)

• Autometrics: A feature in OxMetrics that automates Multi-Path GETS

Autometrics automates GETS modelling of an OLS or IV estimable linear regression

$$y = \beta_0 + \beta_1 x_1 + \cdots + \beta_K x_K + \epsilon$$

where the $\{\epsilon\}$ can be homoscedastic, heteroscedastic and/or autocorrelated

• NOTE: Only the case where $\{\epsilon\} \sim IIN(0, \sigma^2)$ has been extensively studied through Monte Carlo simulation (see in particular Hendry and Krolzig 2005, and Doornik 2009)

• Analytical analysis either not possible or yields limited insight

GETS modelling summarised:

1. Formulate a General Unrestricted Model (GUM)

2. Delete step-wise, along different paths, insignificant regressors at the chosen regressor significance level α ("target size", optional), while checking a range of (optional) diagnostics at each deletion using a different (optional) significance level

3. If simplification results in more than one terminal model, then select the model with lowest value on the chosen information criterion (default: Schwartz), or their union (optional)

Main benefits of GETS modelling:

• Estimation and inference is conducted while controlling for the influence of other variables

• In simulations multi-path GETS compares favourably to other (in-sample) modelling strategies

• GETS modelling results in a parsimonious model that is particularly useful for scenario analysis (conditional forecasting, policy analysis, counterfactual analysis, etc.)

Main disadvantages of GETS modelling:

• Slight tendency to retain irrelevant variables (the more correlated the regressors, the higher the tendency)

• Finite sample behaviour can depend substantially on the properties of the data (regressor inter-correlation, homoscedastic vs. heteroscedastic errors, fat-tailed errors, etc.)

Define k_0 as the number of relevant variables in GUM, k_1 as the number of irrelevant variables in GUM (and so $k_0 + k_1 = K$ total number of variables in the GUM):

• $\hat{k}_0/k_0$ is the relevance proportion or "potency" (analogous to "power" in statistical hypothesis testing)

• $\hat{k}_1/k_1$ is the irrelevance proportion or "gauge" (analogous to "size" in statistical hypothesis testing)

Main statistical properties of Autometrics (default options):

• $E(\hat{k}_0/k_0) \to 1$ as the sample size goes to ∞

• $E(\hat{k}_1/k_1) \to \alpha$ as the sample size goes to ∞

Target size:

• User defined regressor significance level α. For example, if 5% is chosen, then the insignificant regressors at 5% are deleted

Diagnostic test p-value:

• The acceptable diagnostic test significance level. For example, if deleting an insignificant variable results in a diagnostic test p-value above the acceptable level, then the variable is re-included into the model

Branch:

• Suppose we choose a regressor significance level of 5%, and consider the following GUM:

Regressor	Coef.	P-value
x_1	2.851	0.35
x_2	0.343	0.00
x_3	1.069	0.07

The GUM contains TWO insignificant variables (x_1 and x_3) $\Rightarrow$ TWO branches each made up of *paths*

Path:

• A deletion sequence. For example if x_1 is deleted first and then x_3 before no regressors are significant at the chosen regressor significance level, then $\{x_1, x_3\}$ is a deletion path or sequence

Rounds:

• If simplification results in more than one terminal model, then Autometrics initiates a second round by forming a new GUM made up of the union of the terminal models

• Specification search terminates when either only one terminal model results, or when the GUM at round n equals the GUM at round $n - 1$. If this is the case, then a "Tiebreaker" (an information criterion) is used to select among the models

Backtesting:

• Parsimonious encompassing test. By default, this is a joint test of the final model against the initial GUM ("GUM 0"), that is, an F-test of whether the deleted regressors are jointly insignificant at α

OxMetrics basics:

• Load data: File → Open, etc.

• Edit sample/dates: Edit → Change Sample

• Missing values (my recommendation): Set to "missing" by double-clicking the data cell in question

• Graph series: Model → Graphics (or click on the graphics button) → Actual series or All plot types

• Transform data (algebra feature):

  Edit → Algebra (or click on the "Alg" button) → "Code", e.g. "DCOO = diff(COO,1);" → Run (→ Done)

  (NOTE: Case sensitivity in variable names!)

• Create special series (calculator feature): Model → Calculator (or click on the calculator button) → . . .

• *Example.* Edit dates (2007 Econometric Game Case):

• *Example.* Create a differenced series:

Autometrics is a multi-path GETS modelling feature in OxMetrics:

• The objective of Autometrics is to automate Multi-Path GETS specification search of a *data coherent*, *General Unrestricted Model* (GUM) in the form of a linear OLS/IV estimable regression (or regressions)

• Default definition of data-coherency: Stable parameters and Gaussian, serially uncorrelated, homoscedastic errors. NOTE: These assumptions can be relaxed through the "Advanced Autometrics settings", and if the GUM fails one or several diagnostic checks Autometrics proceeds anyway

• GUM: A general model (advice: Not too general!) that includes the variables and lags that are believed to possibly have an impact

• Further reading: Doornik and Hendry (2007a, pp. 70-77), Hendry and Krolzig (2001) (Autometrics is an evolution of PcGets)

Single-equation estimation. *Example*: 2007 Econometric Game, Question 1

• A "rough" GUM:

$$\Delta COO_t = b_0 + b_1 \Delta COO_{t-1} + b_2 \Delta COO_{t-2} + \sum_{j=1}^{11} c_j d_{j,t} + e_t \quad (1)$$

• Formulating a model: (Model →) PcGive → Category: "Models for time series data" → Model class: "Single-equation dynamic modelling using PcGive" (→ Options) → "Formulate"

• Some estimation options (→ Options):

→ White (1980) standard errors: Tick "Heteroscedasticity consistent standard errors"

→ Newey and West (1987) standard errors: Tick "Heteroscedasticity consistent standard errors" *and* "HACSE"

→ Selected diagnostic tests: Tick "Test summary"

• Formulate a model: (Model →) PcGive → Category: "Models for time series data" → Model class: "Single-equation dynamic modelling using PcGive" → "Formulate"

- Estimation options ($\rightarrow$ Options):

• Specify model (... → Formulate):
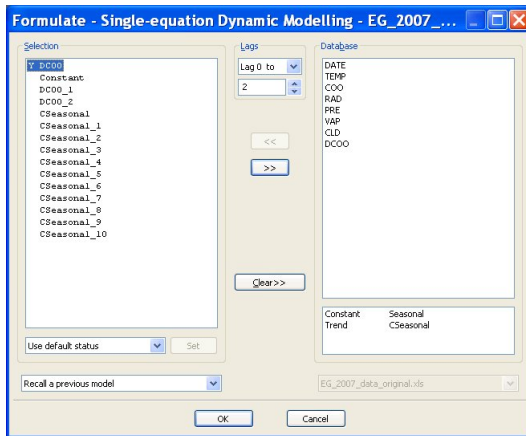
• "Seasonal", "CSeasonal": Seasonal dummies and centred seasonal dummies, respectively

• Estimate with default options: Ok → Ok → Ok

Single-equation GETS modelling with Autometrics. *Example*: 2007 Econometric Game, Question 1

• Recall the "rough" GUM:

$$\Delta COO_t = b_0 + b_1 \Delta COO_{t-1} + b_2 \Delta COO_{t-2} + \sum_{j=1}^{11} c_j d_{j,t} + e_t$$

• The specific model proposed by Autometrics using the default options:

$$\Delta COO_t = b_0 + b_1 \Delta COO_{t-1} + \sum_{j=1}^{3} c_j d_{j,t} + \sum_{j=5}^{11} c_j d_{j,t} + e_t$$

• Level representation:

$$COO_t = b_0 + (1+b_1) COO_{t-1} + b_1 COO_{t-2} + \sum_{j=1}^{3} c_j d_{j,t} + \sum_{j=5}^{11} c_j d_{j,t} + e_t$$

• Specify model:
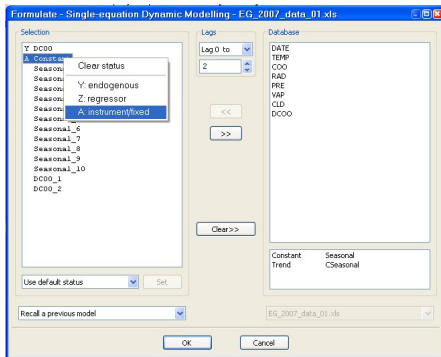
USEFUL FEATURE: Fixing regressors (that is, preventing Autometrics from deleting them). Select the regressors to fix $\rightarrow$ Right-click mouse $\rightarrow$ A: instrument/fixed. NOTE: Do the same thing to define instruments if IV is used instead of OLS

• GETS modelling with Autometrics: Tick "Automatic model selection"

- Main Autometrics options:

  $\rightarrow$ Target size: Regressor and backtesting significance level

  $\rightarrow$ Outlier detection: Neutralises large residuals in the GUM by means of impulse dummies

  $\rightarrow$ Pre-search lag reduction: Speeds up simplification; GENERAL ADVICE: Turn off!

  $\rightarrow$ Advanced Autometrics settings: Tick if default settings are unsatisfactory

• Advanced Autometrics settings:

- Selected advanced Autometrics settings:

  $\rightarrow$ Backtesting: "None" may be preferable if the final model does not encompass the initial GUM. "GUM0" is the initial GUM, which generally does not correspond to the "Current GUM"

  $\rightarrow$ Tiebreaker: The information criterion used to select between terminal models. SC (Schwartz) and min(k) (the model with the least regressors) are the most conservative

  $\rightarrow$ Diagnostic test p-value: The acceptable diagnostic test significance level. If deleting an insignificant variable results in a diagnostic test p-value above the acceptable level, then the variable is re-included into the model

  $\rightarrow$ Standard errors: Ordinary ("Default"), White (1980) ("HCSE") and Newey and West (1987) ("HACSE")

  $\rightarrow$ Heteroscedasticity tests: White (1980)

• "Recursive estimation": Slows down the computations (slightly), but it enables some very useful recursive stability analysis features

• Specific model proposed by Autometrics:

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EQ( 2) Modelling DCOO by OLS
       The dataset is: C:\Documents and Settings\sucarrat\Mis documentos\files\teaching
       The estimation sample is: 1964(8) - 2000(12)

                    Coefficient  Std.Error  t-value  t-prob Part.R^2
DCOO_1              -0.213999      0.04512    -4.74   0.0000   0.0503
Seasonal            -0.199927      0.05880    -3.40   0.0007   0.0265
Seasonal_1          -0.507123      0.05851    -8.67   0.0000   0.1502
Seasonal_2          -0.451573      0.06034    -7.48   0.0000   0.1165
Seasonal_4          -0.707806      0.05885    -12.0   0.0000   0.2540
Seasonal_5          -1.94870       0.06413    -30.4   0.0000   0.6848
Seasonal_6          -3.02784       0.09527    -31.8   0.0000   0.7038
Seasonal_7          -3.77271       0.1275     -29.6   0.0000   0.6733
Seasonal_8          -3.69728       0.1505     -24.6   0.0000   0.5868
Seasonal_9          -1.89487       0.1424     -13.3   0.0000   0.2941
Seasonal_10         -0.176490      0.07692    -2.29   0.0222   0.0122
Constant      U      1.50663       0.06042     24.9   0.0000   0.5940

sigma                0.286776    RSS                     34.9520821
R^2                  0.946555    F(11,425) =      684.3 [0.000]**
log-likelihood     -68.1549      DW                            2.05
no. of observations  437         no. of parameters               12
mean(DCOO)           0.112334    var(DCOO)                 1.49654

AR 1-7 test:     F(7,418)  =     1.0154 [0.4196]
ARCH 1-7 test:   F(7,411)  =     0.78778 [0.5979]
Normality test:  Chi^2(2)  =     2.5460 [0.2800]
Hetero test:     F(12,412) =     0.85756 [0.5908]
Hetero-X test:   F(22,402) =     1.2915 [0.1715]
RESET test:      F(1,424)  =0.00067988 [0.9792]
```

Some further diagnostic tests:

• Residuals graphs: Model $\rightarrow$ Test $\rightarrow$ Graphical analysis $\rightarrow$ . . .

• User specified residuals tests: Model $\rightarrow$ Test $\rightarrow$ Test $\rightarrow$ . . .

• Recursive graphics (VERY useful!): Model $\rightarrow$ Test $\rightarrow$ Recursive graphics $\rightarrow$ . . .

Single equation dynamic forecasting:

• The parsimonious model suggested to us by Autometrics
contains lags and deterministic terms only, so we may readily
generate dynamic forecasts beyond 2000(12)

• Forecasting DCOO dynamically 24 months beyond 2000(12):
Model → Test → Forecast and then
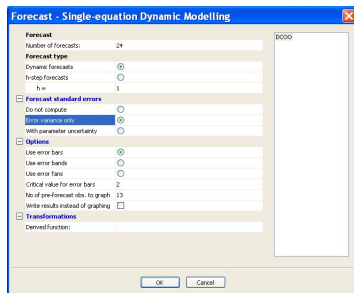
yields (graph on next slide)

Single equation dynamic forecasting (cont.):

• Out-of-sample forecasts of DCOO from 2001(1)-2002(12):
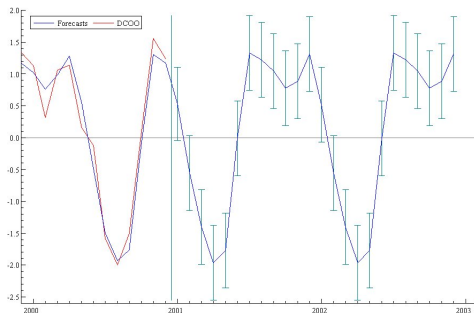
• In order to generate forecasts of the *level* of COO, recall that any variable y_T satisfies $y_T = y_0 + \sum_{t=1}^{T} \Delta y_t$. In other words, tick "Write results instead of graphing" and use Algebra or Calculator (Model → Calculator) to obtain the forecasts of the levels COO

Multiple-equation modelling with Autometrics (two approaches):

1. Seemingly Unrelated Regression (SUR) using OLS/IV, that is, single-equation GETS modelling of each equation separately (requires stationarity of regressors)

2. Simultaneous variable deletion (or non-deletion) across equations using vector diagnostic tests but estimation still by OLS (does not require stationarity of regressors), see Doornik and Hendry (2007b, pp. 29-31). (NOTE: IV estimation not available with this strategy)

$\rightarrow$ Model type: "Unrestricted system" (system of URFs), see Doornik and Hendry (2007b, chapter 3)

Formulate a system: (Model →) PcGive → Category: "Models for time series data" → Model class: "Multiple-equation dynamic modelling using PcGive" → "Formulate"
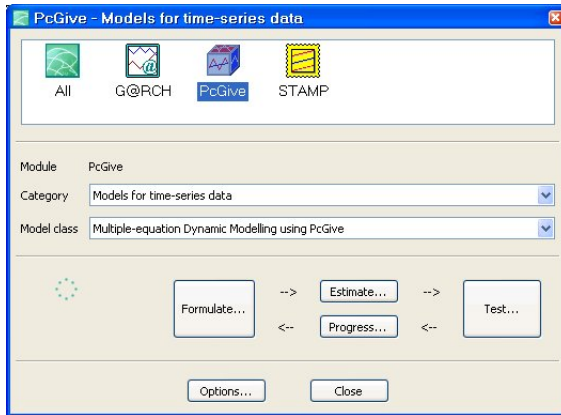
Multiple-equation modelling with Autometrics using second approach. *Example*: 2007 Econometric Game, Question 2

• My GUM: A six-dimensional VAR(2) of
$y_t = (TEMP_t, COO_t, RAD_t, PRE_t, VAP_t, CLD_t)$, with a constant and 11 centered seasonals in each of the six equations:
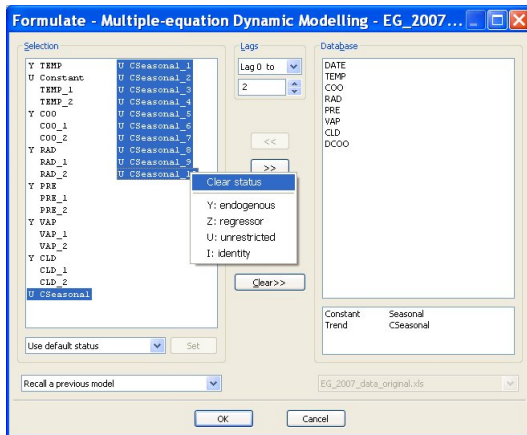
• Fixing variables (that is, restricting Autometrics to keep them) now differs:

  ⋄ Fixing VAR-lags is not possible, only the exogenous regressors can be fixed

  ⋄ Select the exogenous regressors to fix → Right-click mouse → U: Unrestricted

  ⋄ To unfix exogenous regressors, select the regressors to unfix → Right-click mouse → Clear status

• Lag-deletion is undertaken across equations. For example, $TEMP_1$ is either deleted from all six equations or from none, etc.

Results with default settings:

• NOTE: Autometrics simplifies even though the GUM does not pass all diagnostic checks

• Four variables are removed from all of the equations: The second lag of TEMP, VAP and CLD, and CSeasonal_10

Other type of analysis:

• Cointegration analysis (applied on the Unrestricted system, *not* on the simplified model): Model → Test → Dynamic Analysis and Cointegration Tests → . . .

See Doornik and Hendry (2007b, chapter 4)

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